

Harvey Flooding Rescue in Social Media

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Abstract—Social media provided a significant communication platform for rescuing people when Harvey hit Houston area. In this devastating flooding crisis, the overloaded official emergency institutes were not able to respond quickly due to the burst of call for help in a very short period of time. In this circumstance, many volunteers and people who needed help often post their information on social media such as Twitter and Facebook. How to organize volunteers smartly and efficiently to help people is an extremely challenging and significant problem considering the constraints of volunteer’s time slots, urgent priorities, etc. In this paper, we propose three rescue scheduling algorithms to explain how to provide victims timely help by the volunteers on social media.

I. INTRODUCTION

The emergence of the smartphone, social media platform and other high technology sped our community entered into a new era, where every aspect is tagged with ‘smart’. Social media sites such as Twitter and Weibo are experiencing an explosive level of growth. And their functions are not limited to broadcasting users daily observations [1], [2], serving as indicators for finance market [3], forecasting socio-economic disasters [4]–[6]. At the same time, social media also plays a significant role in rescuing people when catastrophic Harvey flooding hit the Houston area. From the early morning of August 26, 2017, Hurricane Harvey made landfall, and in the days following, it dumped trillions of gallons of rain on parts of Texas and Louisiana, spawning unprecedented flooding, leaving many people stranded in waist-deep flooding and desperate for help. So many calls came into 911 in one weekend (Aug 26-27) more than 56,000 within 15 hours making the official emergency response system overwhelmed during this crisis¹. However, social media doesn’t have the constraints of the 911 system, which is limited by the number of phone lines and people available to answer them. Calls for help accumulated on social media platforms such as Twitter where information can flow in real time and is open for anyone to access. Some people posted their address, while others posted the address of a relative or a friend in need of help. As shown in Figure 1, two individuals tweeted the address of locations where people were stranded and needed help.

After Harvey flooded out Houston, people sprang into action to help with rescues. Technically, anyone who sees a public

¹<http://www.sandiegouniontribune.com/opinion/the-conversation/sd-hurricane-harvey-5-ways-social-media-helped-rescue-efforts-20170828.htmlstory.html>

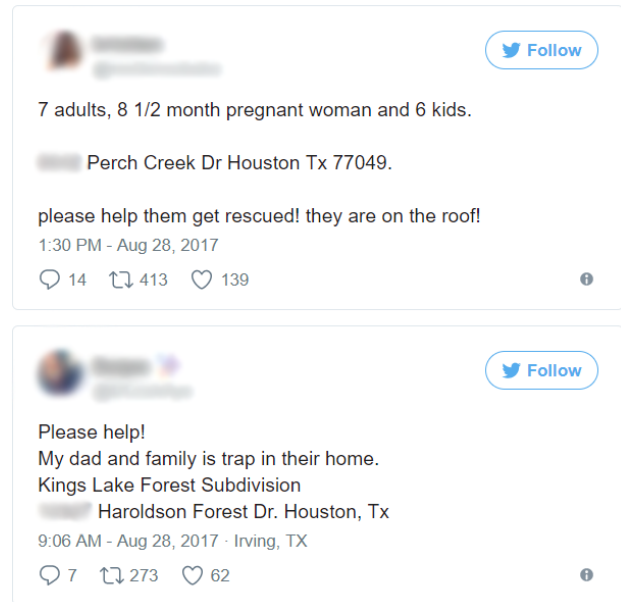


Fig. 1. Example of rescue request tweets for Harvey flooding.

plea for help can respond by dispatching a rescuer in a small boat or large vehicle. However, there are also many volunteers who wanted to rescue flood victims, but did not know how and where and whom to help. One reason is their time availability varies. These volunteers may be available for a whole day service, or simply can only give nearby people a ride with limited capacity, or even focus more on sick people or babies who have high priority in rescue. The limited time slot makes it unhelpful to register volunteers in some official associations. How to connect the individual volunteers limited time slots to schedule rescue work in an efficient way, how to allocate the volunteers’ task in order to minimize his/her time input, considering calling help location, emergence extent, etc. is very important. Additionally, how to optimize the match among the large group of calling and distributed volunteers, considering time, location, and emergency, is an extremely challenging problem. However, these critical segments have not yet been well studied in the disaster relief work.

We propose to design rescue scheduling algorithms, hoping to provide victims with the timely support they needed, filling in gaps that were unable to be filled by the government and

to utilize a logistic regression, to help identify whether a tweet is rescue-related or not.

b) Scheduling Algorithms: Scheduling algorithms are widely used for distributing limited resources among parties that request them based on certain rules, such as efficiency or fairness. The main purpose of a scheduling algorithm is to maximize the utilization of resources and to ensure fairness among the parties using the resource. In this paper, we mainly focus on FCFS [16] scheduling, priority scheduling and hybrid scheduling. Those scheduling techniques have been extensively used in telecommunications, computer systems, logistics, military, among others. Uwe and Ramin [16] demonstrated that there are algorithmic issues in job scheduling where theoretical and applied research can both contribute to a solution, and came up with a new method to improve the utilization of FCFS scheduling. Leung and Whitehead discussed the complexity of determining whether a set of periodic, real-time tasks can be scheduled on $m \geq 1$ identical processors, with respect to fixed-priority scheduling, and showed that the problem is NP-hard in all but one special case [17].

III. INFORMATION RETRIEVAL FROM TWEETS

In this part, three tasks are required in order to obtain full information from tweets.

A. Data Collection and Geo-coding

The study described in this paper uses tweets geolocated to the United States, and are collected over the period from Aug 26 to Aug 30, 2017. We query Twitter API to collect tweets that also have meta-information, including geographical coordinates, places of tweeting, user profile location, and ‘mentions information’ about locations present in the body of the tweet. In cases when no geographical location was found in the tweet text, we proceed to process the geographical coordinates and the self-reported location string in the user’s profile metadata [6].

B. Tweets classifier - SVM

A tweet classifier is built in order to identify whether a tweet is calling for rescue or not. To reduce the computational complexity, only the tweet’s description is used as input in the support vector machine (SVM) classifier. The process begins by constructing a bag of words from the training dataset descriptions by deleting meaningless stop-words such as ‘the’, ‘a/an’, and ‘at’. The resulting bag of words is composed of M words denoted as $[w_1, w_2, \dots, w_M]$ [18]. Each tweet description X is considered as a vector of length M . If the word w_i occurs in its description, then $X(i)$ will be assigned a value of 1; otherwise, it will be 0. Each protest in the training dataset is assigned $Y = 1$ if it is a rescue related tweet, or $Y = 0$ if it is a non-rescue related tweet by manually checking the meaning of its description. In this way, each tweet is converted to a corresponding vector based on the bag of words. By combining all the vectors of tweets, a document term

matrix is built. Eventually, the classifying decision becomes the solution to an optimization problem:

$$\max L_D(\alpha_i) = \sum_{i=1}^N \alpha_i - 1/2 \sum_{i=1}^N \alpha_i \alpha_j y_i y_j x_i x_j \quad (1)$$

such that $\sum_{i=1}^N \alpha_i y_i = 0$ and $\alpha_i > 0$. The decision rule is:

$$f(x) = \sum_{i=1}^N \alpha_i K(x_i, x) + b \quad (2)$$

where $K(x_i, x)$ is a polynomial kernel in our solution. Equation (1) and (2) are explained in detail in [19].

a) Classifier Evaluation: 1000 tweets were manually labeled as either rescue or non-rescue tweet. 70% of the dataset was used for training, and the rest was used as test data. To ensure that the classification results are trustworthy, the performance is carefully evaluated by cross validation, utilizing measurement criteria of precision (positive predictive value), recall (true positive rate) [20], F-measure (a measure that combines precision and recall), and accuracy (the proportion of true results, both true positives and true negatives among the total number of cases examined) [21]. The best classifier is SVM that achieved the best performance, with F-measure of 0.687 and accuracy of 0.93. A couple of well-known classification methods (K-nearest neighbor [22], CART [23], and logistic regression [24]) serve as baseline models.

TABLE I
CLASSIFICATION METHODS COMPARISON.

	Precision	Recall	F_ measure	Accuracy
Log. Regression	0.248	0.658	0.360	0.703
KNN	1.000	0.413	0.584	0.926
CART	0.710	0.579	0.638	0.917
SVM	0.606	0.793	0.687	0.930

C. Priority Determination

Rescue tweets contain some special information, including location, number of people, emergency conditions, and special requirements. To accurately identify flood victims’ emergency conditions, some critical features, such as age, health status, and situations need to be incorporated. We decide whether one rescue request need to trigger emergency rescue by designing a keywords corpus including terms such as ‘*grandma, grandpa, senior, old, baby, kid, pregnant, sick, ill, dangerous*’; when a tweet contains those keywords, the request will be considered high priority.

IV. SCHEDULING ALGORITHM

Since 911 can only serve certain callers at a time, with so many people calling for help at the same time, it’s extremely difficult for everyone to get through. Thus, many people who are in need of rescue turn to social media for help. They may use hashtags such as ‘#HarveySOS’, ‘#HarveyRescue’ and ‘#HoustonRescue’, or may post keywords such as ‘help Harvey victims’. Meanwhile, there are volunteers who are

willing to offer help and have the capacity, such as a boat. However, those volunteers are scattered around the city. Without a coordination center with a well-organized scheduling policy, it's difficult to efficiently assign those volunteers to rescue people who are in need of help. In this paper, we aim to solve this dilemma by applying several scheduling algorithms that will boost the efficiency of this system, and hence speed the rescue work to minimize hurt to victims.

A. The Queuing System And Scheduling Policies

First of all, some terms used in this paper need to be clarified. There are several key elements in a queuing system.

- Server, which refers to any resource that provides the required services. In our case, the volunteer is the server.
- Customer, which refers to someone who requires service. In this paper, it refers to the victim requesting help via posting rescue tweets.
- Calling population, which refers to the population of potential customers. It may be assumed to be finite or infinite (if arrival rate is not affected by the number of customers being served and waiting).
- System capacity, which refers to a limit on the number of customers that may be in the waiting line or system. In this case, we assume it to be unlimited.

Since the volunteer resource is limited, some of the requests have to wait in line for service, thus the queue is formed in the service center. The foregoing system can be mapped into a queuing system with multiple servers. It can be described by using Kendall's notation in the form $A/S/C$ [25] [26], where A denotes the distribution of inter-arrival time, S represents the service-time distribution, and C represents the number of servers of a queuing system. It has been extended to $A/S/c/K/N/D$ where K is the system capacity discipline and N is the size of the calling population [27] [28] [29]. When the final three parameters are not specified (e.g. $M/M/1$ queue), it is assumed $K = \infty$, $N = \infty$ and $D = FIFO$ [30].

In our study, this problem can be modeled by a $M/M/c$ queue by the definition of Queuing Theory. A $M/M/c$ queue is a stochastic process whose state space is a set of $\{0, 1, 2, 3, \dots\}$ where the value corresponds to the number of customers in the system, including any members waiting for service. Several rules applied in this systems are listed below:

- Arrivals occur at rate according to a Poisson process and move the process from state i to $i + 1$.
- Service times have an exponential distribution with parameter μ . If there are less than c requests, some of the volunteers will be idle. If there are more than c jobs, some of the requests have to wait in a buffer to be served.
- The buffer is of infinite size, so there is no limit on the number of customers it can contain since there is no physical limitation.

Many theorems in queuing theory can be proved by reducing queues to mathematical systems known as Markov chains [31]. The model can be described as a continuous time Markov chain with transition rate matrix. The state space $0, 1, 2, 3, \dots$,

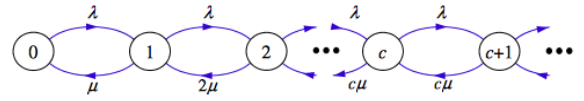


Fig. 3. State Space Diagram for $M/M/c$, λ :arriving rate, μ :service rate

refers to a set of values that the corresponding process may take. The model is a type of birthdeath process. The state space diagram for this chain is described in Figure 3, which indicates how the states of the process can be inter-converted. In $M|M|c$ queues, the arrival rate remains the same as $M|M|1$ queues, but the service rate will depend on the number of servers. The service rate will be n for $n \leq c$. As soon as the number of customers exceeds c , the service rate becomes c as shown in equation μ_c . The service rate, μ_c in this case, will be:

$$\mu_c = \begin{cases} n\mu & n \leq c \text{ for } n=1,2,\dots,c \\ c\mu & n > c \text{ for } n=c,c+1,\dots \end{cases}$$

The probability of having n customers in the service system can be written in a similar way, as we wrote for $M|M|1$ model but with revised service rate.

$$P_n = \left(\frac{\lambda}{\mu_c}\right)^n \times P_0 \quad (3)$$

or

$$P_n = \begin{cases} \left(\frac{\lambda^n}{\mu(2\mu)(3\mu)\dots(n\mu)}\right) P_0 & (\text{if } n < c) \\ \left(\frac{\lambda^n}{\mu(2\mu)(3\mu)\dots(c\mu)(c\mu)^{n-c}}\right) P_0 & (\text{if } n \geq c) \end{cases}$$

namely,

$$P_n = \begin{cases} \left(\frac{1}{n!} \left(\frac{\lambda}{\mu}\right)^n\right) P_0 \\ \left(\frac{1}{c!} \left(\frac{\lambda}{\mu}\right)^c \left(\frac{\lambda}{c\mu}\right)^{(n-c)}\right) P_0 \end{cases} \quad (4)$$

1) *Performance measures of $M|M|c$ Queuing model:* First, we will determine the number of customers in the queue, L_q . In the system, there will be no queue formed until the number of customers are less than or equal to the number of servers. The customer will enter the queue when he finds all the servers busy. Hence, $n - c$ represents the number of customers in the queue. We can write L_q as follows:

$$L_q = \sum_{n=c}^{\infty} (n - c) P_n \quad (5)$$

To determine L_q , substitute $j = n - c$ or $n = c + j$ in the above expression, as given below:

$$L_q = \sum_{j=0}^{\infty} j P_{c+j}$$

P_{c+j} can be written as

$$P_{(c+j)} = \left(\frac{\lambda}{\mu} + \frac{\lambda}{2\mu} + \dots + \frac{\lambda}{c\mu}\right) \left(\frac{\lambda}{c\mu}\right)^j P_0$$

or

$$P_{(c+j)} = \frac{(\rho)^j}{c!c^j} P_0$$

Hence,

$$\begin{aligned} L_q &= \sum_{j=0}^{\infty} \left(\frac{\rho}{c!c^j} \rho^j P_0 \right) \\ &= \left(\frac{\rho^{c+1}}{c!c} \right) P_0 \sum_{j=0}^{\infty} j \left(\frac{\rho}{c} \right)^{j-1} \end{aligned}$$

which can be written as follows:

$$\begin{aligned} &= \left(\frac{\rho^{c+1}}{c! \times c^j} \right) \times P_0 \times \left(\frac{\partial \left(\sum_{j=0}^{\infty} \left(\frac{\rho}{c} \right)^j \right)}{\partial \left(\frac{\rho}{c} \right)} \right) \\ &= \left(\frac{\rho^{c+1}}{c!c} \right) \times P_0 \times \left(\frac{\partial \left(\sum_{j=0}^{\infty} \left(\frac{\rho}{c} \right)^j \right)}{\partial \left(\frac{\rho}{c} \right)} \right) \\ &= \left(\frac{\rho^{c+1}}{c!c} \right) \times P_0 \times \left(\frac{\partial \left(\frac{1}{1-\frac{\rho}{c}} \right)}{\partial \left(\frac{\rho}{c} \right)} \right) \\ L_q &= \left(\frac{\rho^{c+1}}{(c-1)!(c-\rho)^2} \right) P_0 \end{aligned} \quad (6)$$

After determining L_q , the waiting time in the queue W_q is estimated using Little's law as given below: [32], [33].

$$W_q = \frac{L_q}{\lambda}$$

Customers waiting in the service system will be the addition of W_q and service time.

$$W = W_q + \frac{1}{\mu}$$

The number of customers L in the service system will be,

$$\begin{aligned} L &= \lambda W \\ &= \lambda W_q + \frac{\lambda}{\mu} \end{aligned} \quad (7)$$

B. Scheduling Policies

The scheduling policy of a queuing system is crucial because it will largely affect the efficiency of the system [34]. However, it is irrational if we only take efficiency into consideration when dealing with social research. Other factors, such as fairness and well-being of a society, are of equal importance. Thus, they should be considered as well. We take into consideration multiple dimensional elements, and comparisons are made based on those elements. The main purpose is to evaluate the utilization of volunteer resources and explain how the situation can be improved from the viewpoint of resource utilization.

Specifically, to evaluate the utilization and efficiency of volunteer resources, three scheduling policies are proposed and comparisons of resource utilization are made. The first scheduling policy is First Come First Serve, which is used to describe how the volunteer resource is utilized in Hurricane Harvey. Additionally, two scheduling policies are proposed: priority scheduling and hybrid scheduling. The priority scheduling policy takes the significance and urgency of each

request into consideration. And it gives high priority to the old, the sick, the handicapped and the young. If all the requests are with the same priority, it follows First Come First Serve criteria. Lastly, the hybrid scheduling policy is proposed to further improve the whole system.

Algorithm 1: FCFS scheduling with single server

Input: sequence of request[1..n], arrivalTime, serviceTime
Output: The scheduled sequence of requests[1..n]
 Sorting the sequence of request according to their arrivalTime;
for every request $i \in R$ **do**
 waitingT[i]=0;
 for every j from 0 to $i-1$ **do**
 | waitingTime[i]=waitingTime[i-1]+serviceTime[j];
 end
end
for every request $i \in R$ **do**
 totalT[i]=waitingT[i]+serviceT[i];
 averageWT=averageWT+waitingT[i];
 averageTAT=averageTAT+TAT[i];
end

1) *First come first serve:* First Come, First Served is a service scheduling policy whereby requests of customers are sequentially attended in the order that they arrived, without taking into consideration other preferences or priorities [34]. Generally, it is the most well-accepted public service scheduling policy for processing of queues in which customers wait for service that is not prearranged or booked ahead of time. In the analysis of FCFS policy, we assume that all the tweets are processed according to the time they are created. Namely, rescue service is scheduled for the request that has the earliest requesting time. Priority will not be taken into consideration, though some people may be in a critical condition and are in need of service. FCFS scheduling policy has some important details that deserve discussion.

- In the FCFS scheduling, the rescue service is non-preemptive, no matter how long it takes to finish the rescue service.
- Though the FCFS scheduling is fair (intuitively), it is unfair in the sense that non-urgent requests prior to the urgent requests and the time-consuming requests keep a lot of requests wait.
- The average waiting time is relatively long.
- It can be embedded within other scheduling policy.

The FCFS scheduling algorithm for the single-server case is described in Algorithm 1.

2) *Static Priority Scheduling:* Priority scheduling refers to the method of scheduling requests for service based on priority. It involves potential priority assignment, and requests with higher priority will be scheduled first, whereas requests with equal priority are scheduled based on a First-Come-

First-Server (FCFS) basis. The priority can be either static or dynamic. Static priorities are assigned upon the coming of a request, whereas dynamic priorities are assigned depending on the various specific situations. Priority scheduling can be either preemptive or non-preemptive. A preemptive priority scheduling will preempt the service if the priority of the newly arrived request is higher than the priority of the currently ongoing request, while a non-preemptive priority scheduling will simply put the new requests at the end of the queue according to FCFS. The priority scheduling policy also has some essential details as follows:

- Priority scheduling is intuitively unfair since there are queue-jumpers. However, it allows the important or urgent requests to be scheduled first.
- Requests with lower priority may be postponed if there are many requests with higher priority.

Based on our analysis, priority scheduling is necessary. First, it allows the relatively urgent request to be scheduled first. Second, compared to plenty of requests such as the requests for rescuing pets, the requests for rescuing human should be scheduled first especially when the resource is limited. The Static Priority algorithm used in this paper can be seen in Algorithm 2.

Algorithm 2: Priority scheduling with multi-server

Input: R : a sequence of requests, at:arrivalTime, st:serviceTime, iat:interarrivalTime
Input: released, occupied: server
Output: scheduling sequence fo request
Initiation: all the servers are released at beginning
Sort R with regard to starting time of this rescue
for every $I \in R$ **do**
 add I to priority queue implemented by max heap
 Dequeue the root element K of max heap
 Move all servers in occupied which finished before the start of K into released
 if released $\neq \emptyset$ **then**
 m = select(earliestreleased)
 Move m from released to occupied
 else
 m = m + 1
 create Rm and initialize it to \emptyset
 end
 Add K to R_m
end

3) *Hybrid Scheduling:* The hybrid scheduling policy is proposed to further improve the utilization of resource and enhance the efficiency of the queueing system. Basically, the hybrid scheduling is a combination of FCFS scheduling, priority scheduling and dynamic scheduling. The dynamic scheduling method discussed in this paper is different from the paper of Liu and Layland [35]. One of the differences is that the hybrid scheduling policy is non-preemptive. The hybrid scheduling policy discussed in this paper is different from that discussed in real-time scheduling for CPU scheduling. Some of the differences are listed in the following.

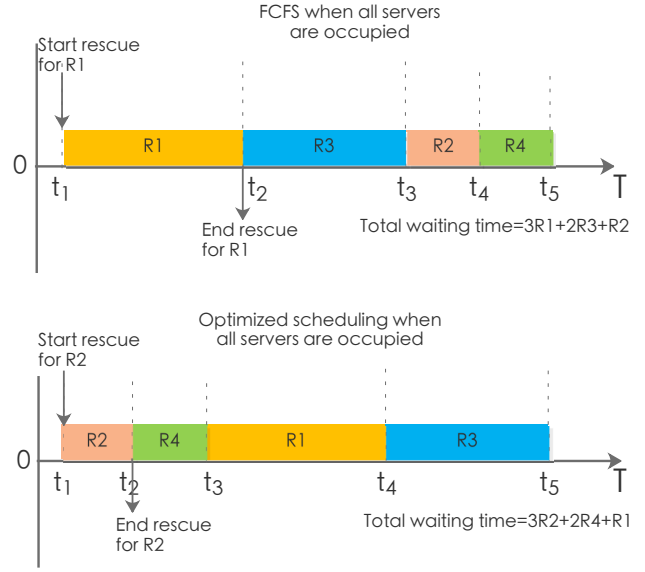


Fig. 4. The hybrid scheduling when all the servers are occupied. The box R_i represents request R_i that arrives in the queue, and the length of a box represents the length of service time. When all the servers are occupied, scheduling the shortest request first could optimize the waiting time for the system

- The hybrid scheduling policy is non-preemptive.
- If the server is idle, incoming requests will be scheduled based on FCFS.
- The priority value is assigned to every request upon its creation, and it can be changed due to an emergency situation. Specifically, if our classification algorithm detects words like “old”, “kid”, “child” and “handicap”, then this tweet will be given higher priority.
- When a server is available, requests with the highest priority will be scheduled first. If all the requests are with the same priority, then the request with the earliest finish time will be scheduled first.

The hybrid scheduling policy discussed in this paper was based on the foregoing rules, and the idea of scheduling request with the earliest finish time can be explained by the Figure 4.

4) *Performance Evaluation:* In order to evaluate the utilization resource and performance of the Request-Server queuing system under different scheduling policies, the average waiting time and delay probability are used to measure the performance.

There is always a trade-off between quality and efficiency in a single-server queue. For instance, the calling center where there is only one server, if good service is provided, then people in line have to wait longer. To evaluate the quality of service for such a system, the fraction of customers who have to wait before receiving services, also known as the delay probability, and the average customer waiting time are two important performance measures. Usually, these two measures should be maintained at certain levels to meet customer expectations [36]. For a single-server $M/G/1$ queue, where

Algorithm 3: Hybrid scheduling

Input: R : a sequence of requests
Input: released, occupied: server
Output: scheduling sequence of request
initialize all the servers' state and requests' state
sort request according to the arrival time
for every request I in R **do**
 if no one waiting in queue **then**
 Move all servers in occupied which finished
 before the start of I into released
 if released server $\neq \emptyset$ **then**
 | select(released server)
 else
 | select a new server
 end
 else
 Add I to the priority queue implemented by max
 heap
 if multiple requests have the same priority with
 root element K' in max heap **then**
 | select the request K with the shortest service
 | time
 else
 | select the root element K of the max heap
 end
 Move all servers in occupied which finished
 before the start of I into released
 if released server $\neq \emptyset$ **then**
 | select(released server)
 else
 | select a new server
 end
 end
end
end

the arrival process is assumed to be a homogeneous Poisson process. Let λ be the arrival rate of the Poisson process, and let m be the mean service time, then, $\rho = \lambda m$ is the traffic intensity of the queue [36]. When $\rho < 1$, it can also be interpreted as the server utilization [36]. By the Poisson property, the delay probability is given by $P_w = 1 - \rho$. When ρ is close to one, almost all customers have to wait before receiving service [36], [37].

V. EXPERIMENTAL RESULTS

1) *Results of Goodness-of-fit Test:* The tweets used in this paper is collected from Aug. 26 to Aug. 30. It is reasonable to test if all the data is governed by the same distribution with the same parameters, since that the data distribution is affected by human habit. Specifically, at night the inter-arrival time of tweets is larger than that of daylight, since most people are asleep. Moreover, all the formulas and equations for the queuing system are held on the condition that the system is stationary. Therefore, the distribution test for data and stationary test for the queue process should be implemented.

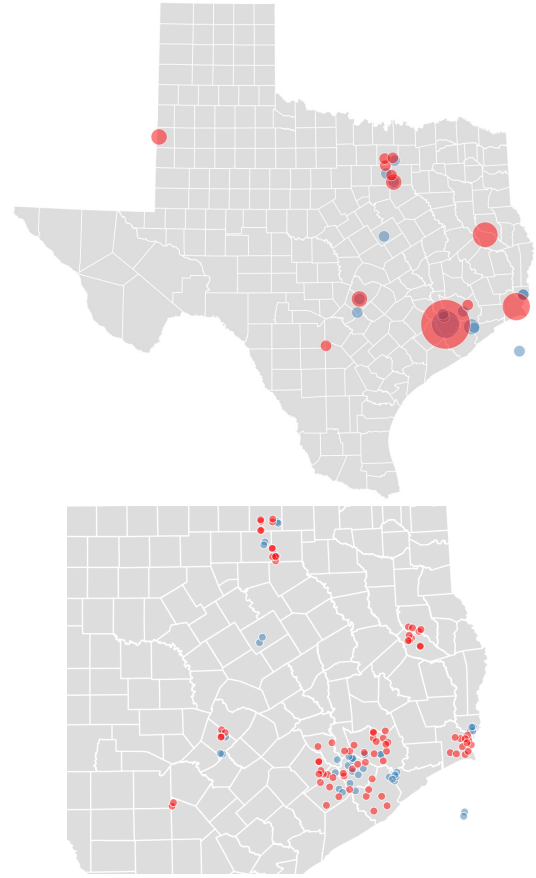


Fig. 5. The upper figure shows scatters of victims and volunteers of Hurricane Harvey in Texas, and the lower figure shows a close look at Houston area, on August 30, 2017. Red dots denote victims who request help from Twitter and blue dots represent volunteers with boats.

The goodness-of-fit test is used to fit data into distribution [38]. We assume that inter-arrival time of rescue tweets from four successive days is governed by the exponential distribution with the same λ . However, the result of the goodness-of-fit test shows that the hypothesis is rejected by small p-value (less than 5%). We also assume that the inter-arrival time on a daily basis is governed by the exponential distribution with different λ value, and it is also rejected. With more experiments being conducted, it shows that the inter-arrival time is governed by the normal distribution. The average of inter-arrival time for the four successive days is 71,67,38 and 32 minutes, respectively. And Figure 6 shows how the data is distributed.

The reason why the average inter-arrival time decreases is that the data used in this paper is just a sample of the full dataset. Moreover, the value of inter-arrival time for the rescue tweets is relatively large as Hurricane Harvey landed in Houston. As the Hurricane Harvey escalated, more and more people were flooded and trapped, more and more people turn to Twitter for help. As a result, there are a few requests asking for help on the first day of Hurricane Harvey, and an increasing number of people ask for help later.

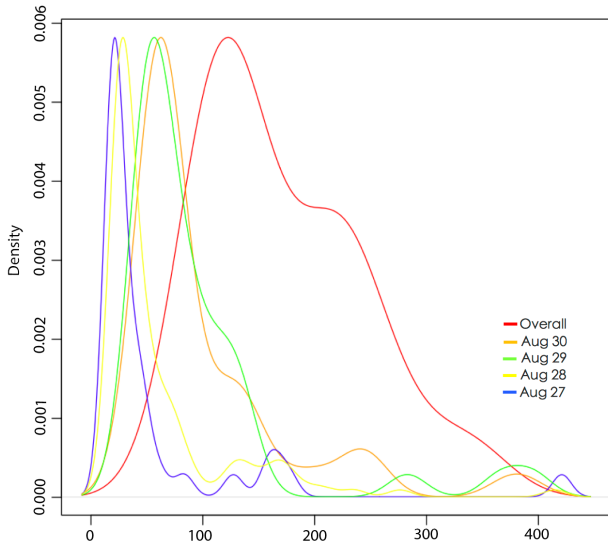


Fig. 6. The probability density distribution of inter-arrival time, from tweets data collected from Aug 27 to Aug 30, 2017.

A similar goodness-of-fit test is performed for the service time, which shows that the service time is governed by the normal distribution with average service time $\mu = 54$ minutes.

2) *Results of Stationary Test:* The stationary test shows the similar pattern with the goodness-of-fit test. Namely, if we combine all the data as input for the stationary test, the null hypothesis will be rejected. That is, the system is not stationary, since we mixed all the data origins from different sources. Therefore, the fundamental assumption upon which formula 1 through formula 5 is not justifiable. Formula 1 through formula 5 can not be used to estimate the queueing system. All the queue-related values are calculated manually after running the scheduling algorithms.

3) *Comparison of Scheduling Policy:* To evaluate the utilization and efficiency of using the public resource (volunteers) during the Hurricane Harvey, we compared three scheduling methods. Basically, the hybrid scheduling algorithm achieved the best performance. First of all, the hybrid scheduling policy has the smallest average waiting time, which is 35 minutes less than that of FCFS scheduling policies, and 39 minutes less than the priority scheduling. Namely, victims will wait for less time before getting rescued if the hybrid scheduling policy is used. Second of all, the system with the hybrid scheduling method has the smallest average queue size. Lastly, the system with the hybrid scheduling method has the smallest ratio of waiting, which indicates that fewer people will wait in line before getting service. The comparisons can be summarized as follows:

- The FCFS algorithm slightly over-performs the static priority scheduling. The static priority has the largest average waiting time of 3.73 hours among the three algorithms, as requests with higher priority cut in line and keep other requests waiting.
- The static priority algorithm is more rational since it takes into consideration the significance and urgency of

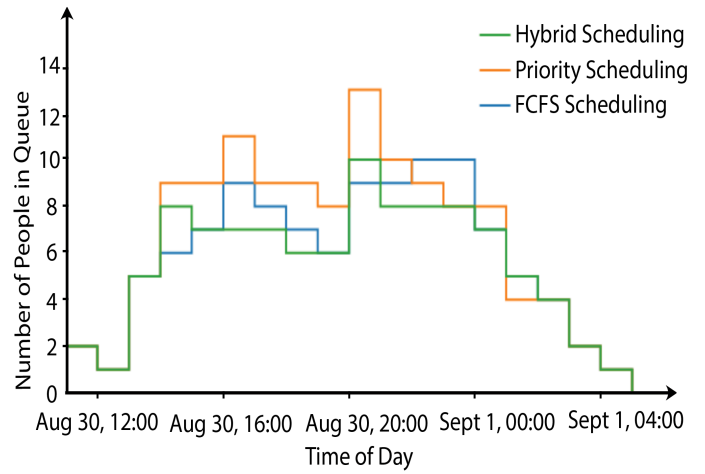


Fig. 7. The number of requests waiting in queue. The increments on the y-axis indicate requests entering the queue, and the decrements on the y-axis signify requests leaving the queue. The y-value at a specific time represents the length of the queue.

a request.

- The hybrid algorithm has the best performance, with the smallest average waiting time of 3.08 hours, which is less than the average waiting time of 3.67 hours in the FCFS scheduling, and 3.73 hours in the static priority scheduling. Moreover, the volunteer resource is fully used while efficiency is guaranteed by having the smallest average time of 3.08 hours in the system. The performance comparisons on average waiting time are visualized in Figure 8.
- Delay probability (the fraction of customers who have to wait before receiving services) for the FCFS, priority scheduling and hybrid scheduling is 0.84, 0.89 and 0.81, respectively. Namely, fewer people will have to wait before being rescued in the hybrid scheduling.

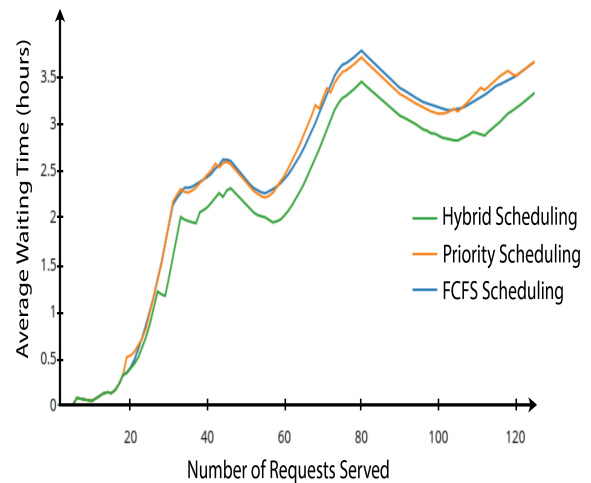


Fig. 8. The average waiting time in the queue, including all the requests that have been served in the system.

The results can be explained for the following reasons.

FCFS over-performs static priority because when all the volunteers are busy, if a request with higher priority cuts in line, it will make all the requests in the line wait. Similarly, the hybrid scheduling minimized such waiting time by scheduling the request with the shortest service time first. As a result, the system as a whole can be optimized with minimal waiting time, and the average number of people waiting in line are the smallest. However, this improvement in performance is at the cost of keeping requests with a longer service time waiting.

The implementation of algorithms on the dataset shows that volunteer resource is insufficient for the rescue. As is shown in figure 8, the average waiting time keeps increasing at the end of every day. Two solutions can be used to solve this problem. One is to increase the service rate of the volunteer. Another way is to increase the number of volunteers in the system. This conclusion is substantiated by the increasing number of tweets looking for volunteers.

VI. DISCUSSION

In this paper, we conducted a study to utilize a public social media platform (Twitter) for flood rescue work. We trained a tweet classifier, which is able to identify flood victims and volunteers. Based on the tweet classification, we designed a series of scheduling algorithms: first come first serve, static priority scheduling, and hybrid scheduling. From the extensive experimental study, we demonstrated that the hybrid scheduling approach is much more efficient than random scheduling for flood rescue. Based on the comparisons of the three algorithms' performance, we conclude that the average waiting time in queue, and average time in the system, can be obviously reduced by implementing the hybrid scheduling policy. Moreover, with the help of text classification techniques and scheduling algorithms, this strategy can be transferred to other disaster rescue work when public resources are needed.

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